

1 WHAT IS CLAIMED IS:

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3 1. A method of visualizing sound fields of individual sound sources using acoustic
4 holography, comprising the steps of:

5 a) calculating sound pressures on a sound source plane using sound pressures
6 measured on a hologram plane;

7 b) extracting a reference sound source locating at a position where a sound
8 pressure has the largest value on the total sound field, and determining the sound pressure
9 at the position as a signal coherent to the reference sound source;

10 c) obtaining a sound field of the reference sound source using the signal coherent
11 the reference sound source;

12 d) eliminating the sound field of the reference sound source from the total sound field
13 to get a remaining sound field, and determining whether any remaining sound field exists;
14 and

15 e) if any remaining sound field exists at step d), applying the step b) to the step d) to
16 the remaining sound field.

1 2. The method of visualizing sound fields of individual sound sources according to
2 claim 1, wherein the sound field of the reference sound source at step c) is obtained by
3 calculating contribution of each of the sound sources in a spectral matrix consisting of auto-
4 spectra at individual points on the sound source plane and cross spectra between different
5 points by using the signal coherent to the reference sound source.

1 3. A computer-readable recording medium for recording a program, which executes
2 the steps of:

3 a) calculating sound pressures on a sound source plane using sound pressures
4 measured on a hologram plane;

5 b) extracting a reference sound source locating at a position where a sound
6 pressure has the largest value on the total sound field, and determining the sound pressure
7 at the position as a signal coherent to the reference sound source;

8 c) obtaining a sound field of the reference sound source using the signal coherent
9 the reference sound source;

10 d) eliminating the sound field of the reference sound source from the total sound field
11 to get a remained sound field, and determining whether any remaining sound field exists;
12 and

13 e) if any remaining sound field exists at step d), applying the step b) to the step d) to
14 the remaining sound field